

# VT430 / Rack control unit

Documentation page: <https://vutlan.atlassian.net/wiki/spaces/DEN/pages/35553336/VT430+Rack+control+unit>

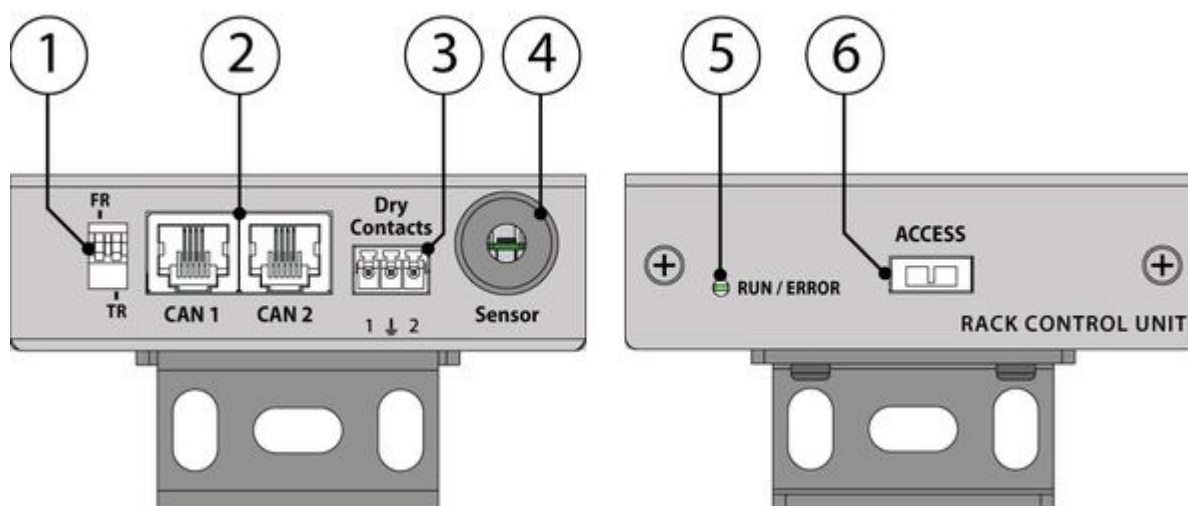
Product page: <https://vutlan.com/can-sensors/25-vt430-rack-control.html>



## Function

The unit has all possibilities for rack control, PIR sensor for door control, 2 dry contacts, temperature and humidity sensors.

## Physical description



1. "TR" - is the nearest switch to CAN inputs. This switch should be turned "ON" on the last sensor in the CAN chain. The last sensor in the long chain with a length of more than 10 meters, terminator should be in "OFF" position.

"FR" - the memory switch, is necessary for reprogramming the module (the switch remote from the CAN connectors).

Do not use DIP switch "FR", it should always be OFF. If this switch is turned ON, the module will turn off. This switch is only needed for programming purposes!

2. "**CAN**" - two equivalent digital connectors RJ12 for the connection of CAN sensors and CAN extensions on a CAN bus, with auto-sensing.
3. "**1, 2**" - Dry contact inputs terminals, can be used for access control.
4. "**Sensor**" - Temperature and humidity sensor
5. "**LEDs**" - LEDs: "**RUN**" - indicates appliance connection status to the main module, "**ERR**" - indicates appliance lost connection to the main module.
6. "**PIR**" - Door IR access sensor. Use white sticker supplied to control the door open/closed.

## Technical specifications

Feature	Description
Type / Network interface	CAN digital sensor
Usage	IR, humidity, and temperature sensor; x2 dry contact inputs (digital inputs);
Product dimensions	(Width, Height, Depth) 89 x 27.1 x 48.2 mm
Packing weight	270 g
Power supply	Power is supplied over the CAN bus
Power Consumption	Power Consumption
Operating temperature	Optimal temperature range: -10° C to +80° C Extended temperature range: -40° C to +100° C
Mounting possibilities	Desktop Indoor Rack-mountable Wall mount
Max. distance from the unit	225 m
Measured Humidity	0 ... 95% RH
Humidity accuracy	3%
Measured Temperature	-10 ... +85 °C
Temperature accuracy	1 °C
IR sensor distance	minimum 1 cm., maximum 3-4 cm.
Inputs terminals	Dry contacts / Digital inputs: x2 contacts (pitch 3,5mm, type IN) RJ-12 ports: x2
Status Indicators	Red / Green Led
Manufactured in (country)	Manufactured in Slovak Republic, E.U.
HS Code	8471 50 000
Daisy chain	Yes, possible using CAN bus



## Installation

There is a mounting bracket on the unit. Fix unit by M5 or M6 bolts on the cabinet or the rack profile in front of the door. Glue the white sticker on the door in front of the unit IR sensor. Connect CAN input of the unit by RJ11/RJ12 cable supplied to the CAN input of previous CAN unit or monitoring system. The red LED lights up. Match the TR bus terminators on the attached CAN units. CAN bus terminators TR (position 2 in VT450) should be in the ON state only at the end CAN units port and in Off states (1,2) for all intermediate units. One CAN bus can have not more than 8 CAN units, sensors, and/or another CAN device.

If necessary, connect dry contacts, door sensors, or triggers to the unit.



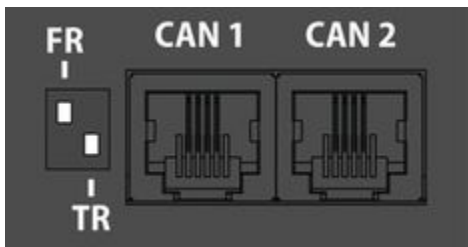
### Connection

To connect CAN unit to the system, open interface and go  CAN Configuration  Select tab CAN.

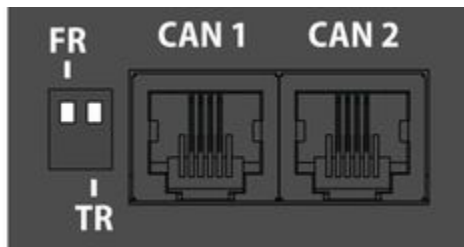
Click "Configure" and wait. The system starts the CAN bus line survey, displays the list of connected CAN units and sensors. On the CAN devices, the green LEDs light up.

If you will go now to the "System tree", there you will see new CAN devices and/or new CAN sensors. Wait for a little or renew the tree.

If the survey is reset after clicking "Configure", it means that the line is not connected (bad cable and/or bad connectors) or not matched terminators on the bus. It is necessary to check and change the status of the line or the TR terminations.



pic.1.1: FR is OFF, TR is ON.



pic.1.2: FR is OFF, TR is OFF.

### CAN devices connection

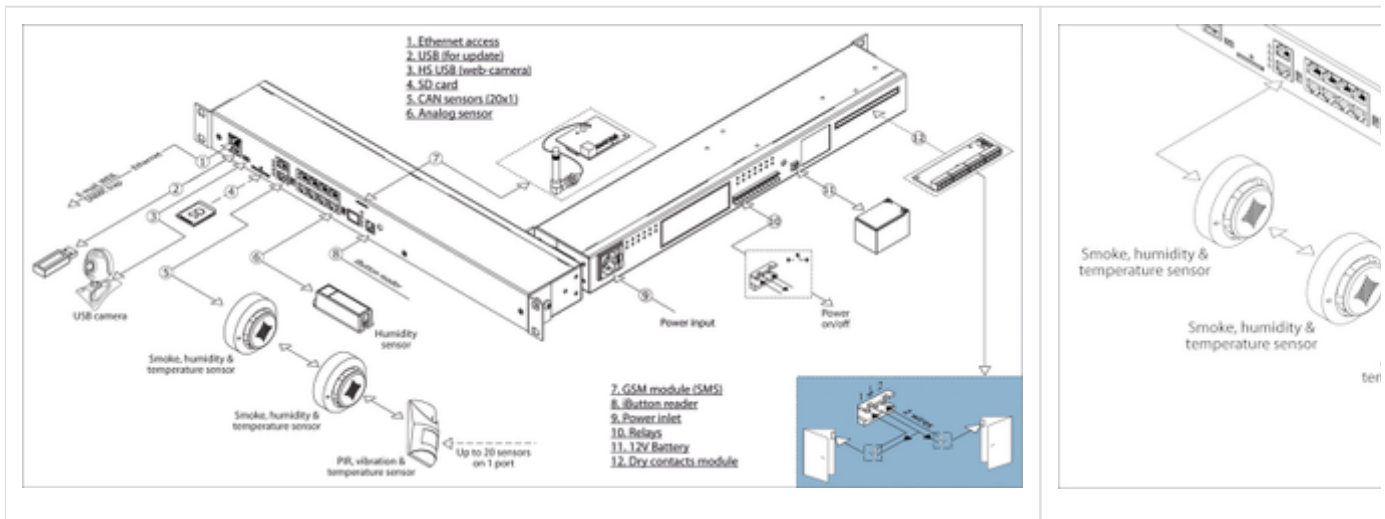
### CAN sensors and CAN units connection

1. Connect CAN devices to any port CAN1 or CAN2 on the monitoring system using a cable supplied. CAN sensors can also be connected to the port of another CAN sensor or CAN unit which is connected to the CAN bus. Determination of the devices and their connection is done through a web interface.

You can connect up to a maximum of x12 CAN sensors and CAN devices together on one CAN bus (approximately)!

If you want to connect more than x12 CAN units, you need to use [CAN-12V-1A / CAN Power Supply](#)

2. The TR should be "ON" for the last sensor on each bus "CAN 1" and "CAN 2". See section "TR" below.



This procedure applies to the following sensors, which are supported by the appliance and are connected to the CAN ports:

CAN sensors, modules:

- [VT408 / Extension unit](#)
- [VT430 / Rack control unit](#)
- [VT440 / Dry contacts unit](#)
- [VT460 / Smoke, humidity, and temperature...](#)
- [VT470 / PIR, vibration and temperature sensor](#)
- [VT490 / Humidity and temperature sensor](#)
- and other...

CAN extension unit:

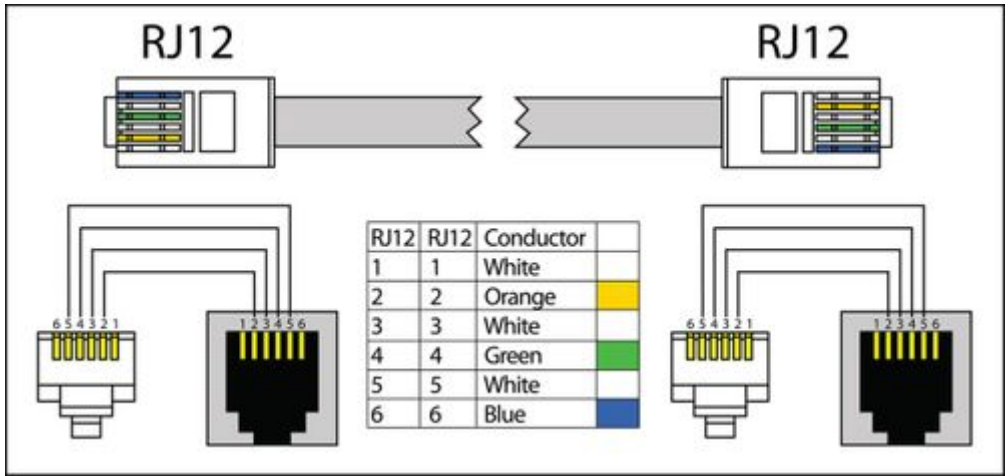
- [VT408 / Extension unit](#)

Read more about [Setting up CAN sensors](#).

### ***Used cable and limit line length***

The maximum length of the CAN line in Vutlan monitoring systems is **225 m** due to limitations on the ohmic resistance of cables with RJ12 connectors.

It is advisable to use two or three pairs of cables such as UTP Cat3.5.6 with 24AWG with a copper core. It is possible to use a 4-wire or 6-wire TRONIC or UTP CCA cable, but the maximum CAN line length will be reduced.



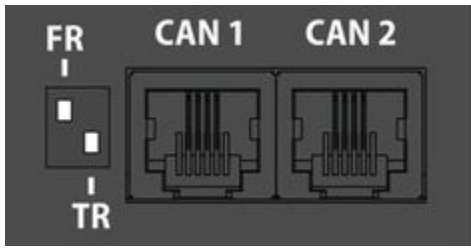
TR termination switch

The last sensor TR switch on a CAN chain must always be terminated, ( switched ON ). Sensors on a CAN bus that is in the middle should have TR switched OFF.

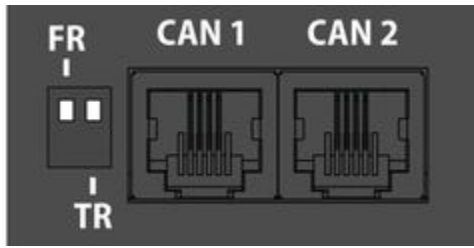
FR should always be OFF.

TR switch is always the DP switch nearest to the CAN bus.

Only older Vutlan models have an FR switch.



pic.1.1: FR is OFF, TR is ON.



pic.1.2: FR is OFF, TR is OFF.

Adding CAN modules and sensors

To connect the CAN module or CAN sensor to the CAN bus of the system, go to the interface >> CAN configuration panel >> Select the CAN1 or CAN2 tab (select the connected physical CAN1 or CAN2 port on the master module).

Click the "Configure" button and wait. The system will start CAN bus polling, soon it will display the data lines and write "Done!". The modules and sensors connected to the CAN input will appear in a tab in the list. Click the Apply button and then Restart.

The green LED "CAN status" of the device will light up.

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Monitoring & Control Systems

operator

- Overall stats
- System tree
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- Map
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- CAN configuration**
- Graphs
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### CAN configuration

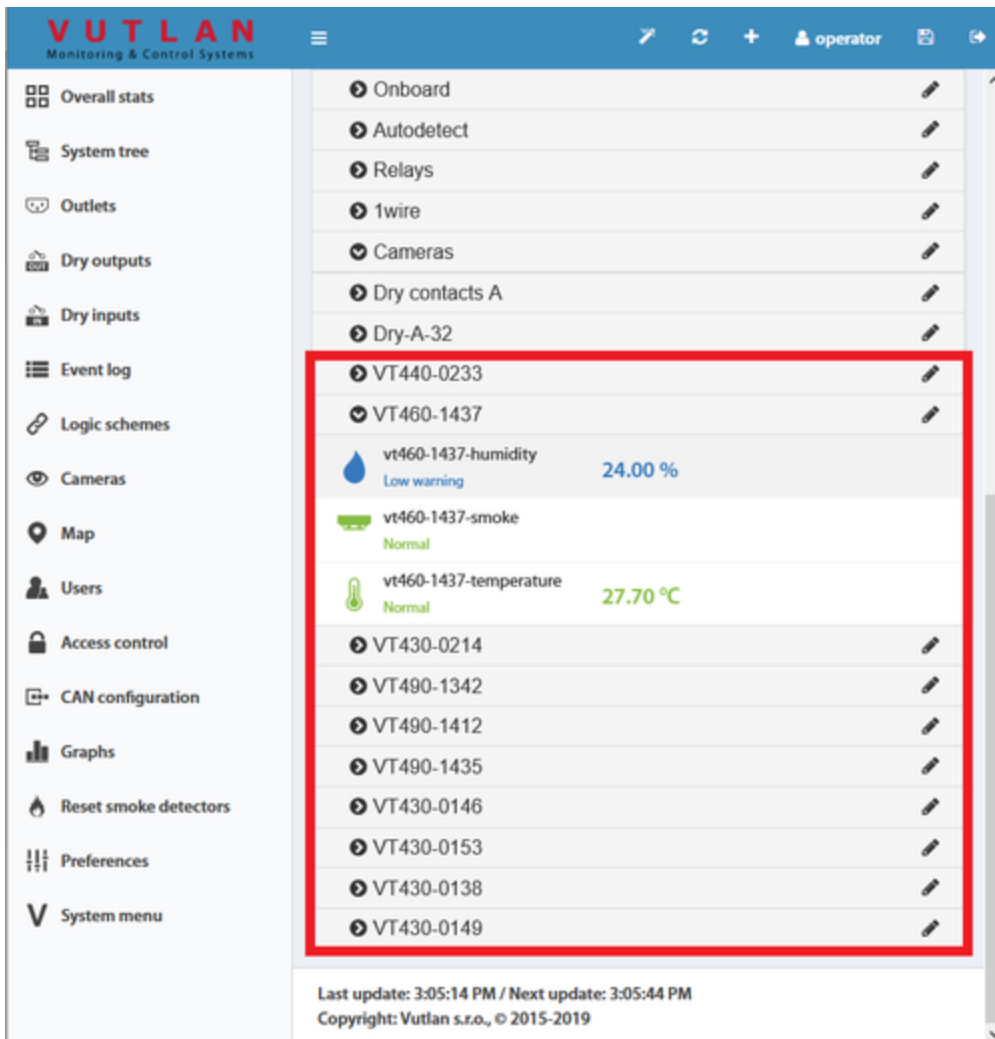
CAN 1

Network name: can0  
State: up  
Mode: normal  
Last update time: 2020-05-13 8-42-42 PM

Product code	Description
VT440 (6)	32/64 dry contacts
VT460 (7)	Smoke, temperature, humidity
VT430 (10)	PIR sensor, 2 dry, humidity, temperature
VT490 (8)	Temperature, humidity
VT490 (8)	Temperature, humidity
VT490 (8)	Temperature, humidity
VT430 (10)	PIR sensor, 2 dry, humidity, temperature
VT430 (10)	PIR sensor, 2 dry, humidity, temperature
VT430 (10)	PIR sensor, 2 dry, humidity, temperature
VT430 (10)	PIR sensor, 2 dry, humidity, temperature

Refresh Save Configure Restart

Go to panel "System Tree" to see the new devices or new sensors. The article numbers for CAN devices are VT4xx. If they do not appear, wait, or refresh.



If after clicking the "Configure" button the poll is reset to the phrase "Update", then the line is not connected or the terminators on the bus are not agreed. It is necessary to check and change the condition of the **TR terminators** (See "TR termination switch" section above) on the modules or check and possibly change the **connection cables**.

Warning: If the bus is not matched, that is, there are bad contacts or bad cables, or the TR terminator is in the "ON" position on the intermediate devices (position 2 on the VT408), or the line is too short for matching on both CAN end devices, CAN on this line can work malfunctioning or the line as a whole may not function. (CAN line failure may occur if the parallel CR switch is in state 1, must be in OFF).

## LEDs

CAN sensors have LEDs that indicate the following states:

- Red continuous light, green flickers - no communication with the master module
- Red continuous light, green is off - there is a connection with the master unit, but is not included in the monitoring system (not configured)
- Red is off, Green continuously light - work as part of a monitoring system
- All LEDs are off: no power or sensor is defective.

Maximum cable length test

Model	Description	50m	100m	150m	200m
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VT408	Sensor extension unit		ok		
VT408DIN			ok		
VT430	Rack control unit		ok		
VT440	Dry contacts unit		ok		
VT460	Smoke, humidity, temperature		ok		
VT490 / VT490i	Dual humidity and temperature sensor / Pressure, humidity & temperature sensor		ok		

see also:

- [VT408 / Extension unit](#)
- [VT408DIN / Extension unit](#)
- [VT430 / Rack control unit](#)
- [VT440 / Dry contacts unit](#)
- [VT460 / Smoke, humidity, temperature sensor](#)
- [VT490 / Humidity and temperature sensor](#)
- [VT450 / Pressure, humidity and temperature sensor](#)
- [CAN-12V-1A / CAN Power Supply](#)

## Setting up CAN

### Enable CAN

Inside the web interface of the system go to >> Preferences menu >> Network tab >> Enable CAN >> Save >> Save settings to flash (An icon in the top right corner of the web interface)

### Configuration

CAN bus is used for connection of CAN sensors and CAN modules. The device has two independent CAN nodes: CAN1 and AN2.

Before using CAN sensor module, CAN bus must be configured to operate with this CAN sensor module. To configure CAN bus go to "Main menu" >> "CAN" menu, which in turn has two identical tabs - one for each node.

**CAN configuration**    username: guest

CAN 1    **CAN 2**

**Network name**    can0

**State**    up

**Mode**    normal

**Last update time**    2015-02-04 9:26:29 AM

Product code	Description
sc470 (1)	Motion, vibration, temperature
sc408 (4)	8 analog (with auto detecting) sensors

Refresh    Save    Configure    Restart

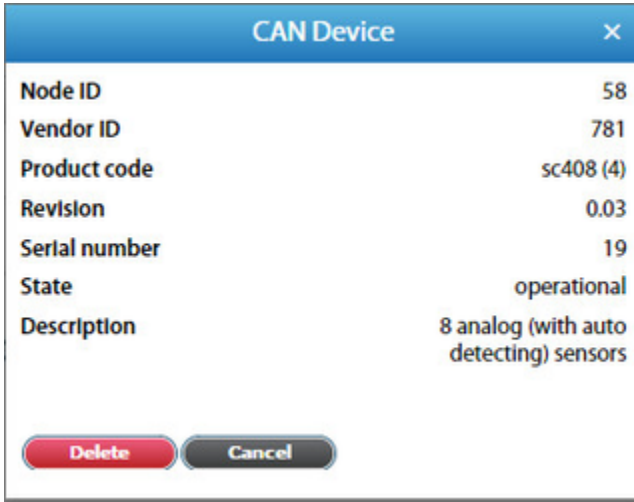


Each station tab contains current information on the status of the node and a list of CAN sensor modules connected to this node.

The following operations can be carried out on the CAN bus node:

- Refresh - updates the current information on the status of the node;
- Configure - launches configuration process of the nodes for CAN sensor modules connected to it, the old configuration is lost
- Save - saves the list of CAN sensor modules in flash memory;
- Restart - restarts the CAN bus node.

To delete a CAN sensor module, click on the desired module. A modal window will pop up. Press "Delete" and confirm.



To set up a CAN bus node for operation with the CAN sensor module, connect CAN module to CAN network and run corresponding configuration procedure in the web interface using the command "Configure". The configuration process is displayed at the bottom of the tab and lasts approx. 2 minutes. Detected modules will be added to the list of modules during the configuration process. After completing configuration the node returns to its normal operation. Sensors of detected CAN modules are added to the tree of elements.

The names of the sensors are automatically set in the form {module name}{serial number}-{type of sensor} and can be edited.

If you need to remove CAN sensor module from the configuration list use command Delete, then use command "Save" to apply the changes you made and restart the node using the command Restart.

- [Configuring VT408](#)

Drawings



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